DOC2PPT: Automatic Slide Deck Generation from Documents

AAAI'22



Tsu-Jui Fu



William Wang



Daniel McDuff



Yale Song





DOC2PPT

• Generate a slide from an academic paper



Image-Chat

Speaker b : a & b .
We apply a set of 215 possible style traits , using an existing set from shuster et al .



Human Evaluations on IMAGE-CHAT

Ablation study for both retrieval and generative models
 What is the best of both worlds ?
 Resnet 152, resnet densenets.
 We ask the evaluators to choose the two possible utterances :



Retrieval Models

- Two major types of dialogue model :

- In the retrieval model , the three modalities are fed into a combiner module

- Resnet 152, resnet densenets.

Dialogue decoder : dialogue decoder the encoding from the image
 Style encoder to obtain its representation rs.



Conclusion

- Can be studied in future work .
- (zhang et al . , 2018)
- Humans can relate to social dialogue agents
- Retrieval models outperformed their generative models
- A new dataset is made of a new dataset .

DOC2PPT

- Multi-modal summarizer ullet
 - **Text Summarization + Figure Retrieval + Multi-Page** \bullet



Figure 2: The TRANSRESNETRET multimodal architecture for grounded dialogue. There are several options: different image encoders (ResNet152 or ResNeXt-IG-3.5B), text encoders (shared or separate Transformers for history and response), and different multimodal combiners (sum or attention-based).

per as ResNet152 features. We used the implementation provided in the torchvision project (Marcel and Rodriguez, 2010). The second is a ResNeXt $32 \times 48d$ (Xie et al., 2017) trained on 3.5 billion In-

logue tasks previously (Yang et al., 2018; Mazare et al., 2018). We use a Transformer with 4 layers, 300 hidden units, and 6 attention heads. The outputs are pooled (mean) to give a final vectorial encoding.

We pretrain the entire encoder following the setup described in Mazare et al. (2018); we train two encoders on a next-utterance retrieval task on a Reddit dataset of dialogues containing 1.7 billion pairs of utterances, where one encodes the context and another the candidates for the next utterance. their dot product indicates the degree of match, and they are trained with negative log-likelihood and k-negative sampling. We then initialize our system using the weights of the candidate encoder only. and then train on our task in either generative or retrieval mode.

4.1 Retrieval Models

Multimodal combiner module We consider two possible combiner modules for the inputs: Multimodal sum combiner (MM-sum): Given an input image, style trait and dialogue (I, S, D), to gether with a candidate response C, the score of the final combination is computed as s(I, S, D, C) : $(r_I + r_S + r_D) \cdot r_C.$

Multimodal attention combiner (MM-att): A more sophisticated approach is to use an attention mechanism to choose which modalities are most relevant for each example by stacking Transformers. We concatenate the three representation

Text **Summarization**



Multi-Page .

.

- Crawl paper-slide pairs from AI conferences
 - Computer Vision (CVPR, ECCV, ...)
 - Natural Language Processing (ACL, NAACL, ...)
 - Machine Learning (ICLR, ICML, ...)
- **5,873** in total
 - 4,686 / 592 / 595 (train / val / test)
- To prepare the data for training, needs some **preprocessing** in advance

- Extract **text content** from a slide
 - Azure CV to do **O**ptical **C**haracter **R**ecognition (OCR)



- Learning Over-Parameteiized –Neural
- Networks on Structured Data
- Yingyu Liang@UWLMadison
- Joint work with Yuanzhi Li@Princeton -Y Stanford



- Our Work
- Is there a simple theoretical explanation?
- Our work: Yes for two-layer NN on clustered data!
- Poster: Tue Poster Session A #143

- Match sentences from slide to paper
 - **Extractive**-based summarization



- Match sentences from slide to paper
 - Extractive-based summarization



Slide

- Match figures from slide to paper ullet
 - **CNN feature** to do similarity matching \bullet

TrackR-CNN [59]





SMOTSA MOTSA MOTSP TP↑ FP↓ FN↓ Method (a) KITTI MOTS Dataset [59] - Cars Mask R-CNN [18]+[T[6]] 74.9 85.8 140 faskTrack R-CNN [66] 894 753 86.1 87.8 88.8 TrackR-CNN [59] (b) KITTI MOTS Dataset [59] - Pedestrian Mark R.CNN USIATTIGIL 44.6 63.8 MaskTrack R-CNN TrackR-CNN [59] 45.9 64.6 65.1 280 267 (c) MOTSChallenge Dataset [59] Mask R-CNN [18]+IT[6]] 48.6 65.5 MaskTrack R-CNN TrackR-CNN [59] 66.7 19,882 1,882 (d) YouTube-VIS Dataset [66] Mask R-CNN [18]+[T[6]] 33.7 MaskTrack R-CNN [66] 34.1 34.6 35.1 47.2 48.3 50.4 78.7 2,767 789 79.8 2,801 **778** 80.8 2,866 785 580 546 481





		DiffCat	Cat	Cat&attr	Cat&cat	WithoutDis
	0.4		1.8	1.9		6.6
GroundeR [35]		60.2	38.5	35.7	38.9	
Deaf-GroundeR	2.2	7.7	7.9	8.0	8.0	27.1
Shuffle-GroundeR		41.8	28.6	27.2	27.6	58.5
Obj-Attr-GroundeR	15.2	53.1	32.6	29.6	32.7	68.8
MattNet-refCOCO	8.7	22.7		16.7	18.9	42.4
MattNet [44]			45.2	42.5	45.8	
CM-Att-Erase [27]		71.3	47.1	43.4	48.4	80.4
SCAN [22]+MattNet	18.8					
MattNet-Mine	33.8		54.4	46.8		78.4



Figure from Paper

Slide

- Match figures from slide to paper
- Not always perfect (currently 50.5% F1)
 - Leave as future work for **better label** to learn from



- Match figures from slide to paper
- Not always perfect (currently 50.5% F1)
- Apply human labeling for testing set
 - Golden testing set for fair evaluation

- Remove the **progressive** page
 - **OCR cover rate** > 80% (Acc ~90%)
 - Keep the **last** one



- Generate pages for each section and combine them all
 - BERT to match **text** (page) with **paragraph** (section)
 - Consider **continuity**

page 1 page 2 page 3	page 4	page 5	page 6
----------------------	--------	--------	--------

- Generate pages for each section and combine them all
 - BERT to match text (page) with paragraph (section)





















Progressive

Removing

•

•



Progressive

Removing

•

•

			Paper			Slide	
	num	#section	#sentence (per section)	#figure	#page	#sentence (per section)	#figure
Train	4,686	6.9	42.9	8.3	16.9	8.1	2.4
Val	592	6.9	42.6	8.3	16.8	8.1	2.5
Test	595	6.9	42.4	8.4	16.5	8.1	2.6
Test (Human)			-				2.3

- Distribution of **#sentence** and **#figure** in slide
 - Similar between train, val, and test



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



- Recurrent extractor to build the slide step-by-step
 - [OBJ], [PAGE], [SECTION] token
 - Section-based generation and classification for extraction



Model (HSE)

- Hierarchical Slide Extractor (HSE)
 - Different RNNs for section-, page-, and object- level



TextFigure Module

- Constrain the **coherence** between figure-text
 - Co-train with HSE
 - Related figure-text should be **close on embedding space**



TextFigure Module

- Right figures put with right texts
 - Filter out unrelated and add unused related figures



Paraphrasing Module

- Rewrite extracted sentences as **slide-style**
 - Seq2seq model (w/ copy attention)





Fig. 3. a: The method proposed by Sadeghi and Foxyth [2] quantizes each cell into one of 256 pre-defined clusters. Nearest neighbour search is a significant bottleneck in their technique. In this paper we use hierarchical clustering instead of flat clustering b: each cell is first quantized into one of the 16 clusters. c: Depending on the first level, the cell is clustered into one of 16 clusters in the respective group in c. Note that hierarchical clustering reduces the number of comparisons from 256 per cell to two stages of 16 comparisons per cell.

3 Hierarchical Vector Quantization

Several optimization techniques have been employed to speed up Deformable Paris Model object detectors. The fastest was proposed by Sadeghi and Forsyth [2] This is nearly two orders of magnitude faster than the original implementation of [21]. The key to their success is a vector quantization technique that decreases the computation demand by a large factor. They vector quantize HOG features and compute template scores by indexing certain look-up tables and adding their scores.

We use vector quantization for the same purpose but with a slightly different approach. The main computation buttleneck in [2] is vector quantization. They need 70ms per image to quantize HOG features for one image. The high computational demand is into to the fact that each HOG cell needs to be compared against every one of 256 cluster centers. (Figure 3, a). We use a hierarchical clustering technique to speed up this process. We first cluster each cell into 16 clusters (Figure 3, b). Then according to the nearest cluster (Figure 3, c). We pre-compute clusters using the means algorithm.

Our experiments show that the proposed hierarchical clustering technique leads to a negligible loss of 0.001 in mAP. In contrast, the speed-up gain is about $8-6\mathrm{dd}$.



Fig. 3. a: The method proposed by Satelphi and Forsyth [2] quantizes each cell into one of 256 pre-defined clusters. Nearest neighbour search is a significant bottleneck in their technique. In this paper we use hierarchical clustering instead of flat clustering b: each cell is first quantized into one of the 16 clusters. c: Depending on the first level, the cell is clustered into one of 16 clusters in the respective group in c. Note that hierarchical clustering reduces the number of comparisons from 256 per cell to two stages of 16 comparisons per cell.



3 Hierarchical Vector Quantization

Several optimization techniques have been employed to speed up Deformable Paris Model object detectors. The fastest was proposed by Sadeghi and Forsyth [2] This is nearly two orders of magnitude faster than the original implementation of [21]. The key to their success is a vector quantization technique that decreases the computation demand by a large factor. They vector quantize HOG features and compute template scores by indexing certain look-up tables and adding their scores.

We use vector quantization for the same purpose but with a slightly different approach. The main computation bottleneck in [2] is vector quantization. They need 70ms per image to quantize HOG features for one image. The high computational demand is due to the fact that each HOG cell needs to be compared against every no of 256 cluster centers. (Figure 3, a). We use a hierarchical clustering technique to speed up this process. We first cluster each cell into 16 clusters (Figure 3, b). Then according to the nearest cluster (Figure 3, c). We pre-compute clusters using k-means algorithm.

Our experiments show that the proposed hierarchical clustering technique leads to a negligible loss of 0.001 in mAP. In contrast, the speed-up gain is about 8-fold.





Fig. 3. a: The method proposed by Sadeghi and Forsyth [2] quantizes each cell into ne of 256 pre-defined clusters. Nearest neighbour search is a significant bottleneck in their technique. In this paper we use hierarchical clustering instead of flat clustering by each cell is first quantized into one of the 16 clusters. c: Depending on the first level, the cell is clustered into one of 16 clusters in the respective group in c. Note that hierarchical clustering reduces the number of comparisons from 256 per cell to two stages of 16 comparisons per cell.



3 Hierarchical Vector Quantization

Several optimization techniques have been employed to speed up Deformable Paris Model object detectors. The fastest was proposed by Sodegii and Forsyth [2] This is nearly two orders of magnitude faster than the original implementation of [21]. The key to their success is a vector quantization technique that decreases the computation demand by a large factor. They vector quantize HOG features and compute template scores by indexing certain look-up tables and adding their scores.

We use vector quantization for the same purpose but with a slightly different approach. The main computation bottleneck in [2] is vector quantization. They need 70ms per image to quantize HOG features for one image. The high computational demand is due to the fact that each HOG cell necks to be compared against every one of 256 duster centers. (Figure 3, a). We use a hierarchical clustering technique to speed up this process. We first cluster each eell into 16 clusters (Figure 3, b). Then according to the nearest cluster (Figure 3, c). We pre-compute clusters (high encans algorithm.

Our experiments show that the proposed hierarchical clustering technique leads to a negligible loss of 0.001 in mAP. In contrast, the speed-up gain is about 8-fold.





Hierarchical Vector Quantization

- We use a hierarchical clustering technique to speed up this process.
- We use vector quantization for the same purpose
- but with a slightly different approach.
- Then according to the nearest cluster in the first step we compare against
- 16 other clusters to find the nearest cluster (Figure 3, c).
- We pre-compute clusters using k-means algorithm.
- Our experiments show that the proposed hierarchical clustering technique leads to a negligible loss of 0.001 in mAP.





Fig. 3. a: The method proposed by Sadeghi and Forsyth [2] quantizes each cell into ne of 256 pre-defined clusters. Nearest neighbour search is a significant bottleneck in their technique. In this paper we use hierarchical clustering instead of flat clustering by each cell is first quantized into one of the 16 clusters. c: Depending on the first level, the cell is clustered into one of 16 clusters in the respective group in c. Note that hierarchical clustering reduces the number of comparisons from 256 per cell to two stages of 16 comparisons per cell.



3 Hierarchical Vector Quantization

Several optimization techniques have been employed to speed up Deformable Parts Model object detectors. The fastest wave proposed by Sadeghi and Forsyth [2] This is nearly two orders of magnitude faster than the original implementation of [21]. The key to their success is a vector quantization technique that decreases the computation demand by a large factor. They vector quantize HOG features and compute template scores by indexing certain look-up tables and adding their scores.

We use vector quantization for the same purpose but with a slightly different approach. The main computation buttleneck in [2] is vector quantization. They need 70ms per image to quantize HOG features for one image. The high computational demand is due to the fact that each HOG cell needs to be compared against every one of 256 dustre centers. (Figure 3, a). We use a hierarchical clustering technique to speed up this process. We first cluster each eell into 16 clusters (Figure 3, b). Then according to the nearest cluster (Figure 3, c). We pre-compute clusters (high encasa slop) means algorithm.

Our experiments show that the proposed hierarchical clustering technique leads to a negligible loss of 0.001 in mAP. In contrast, the speed-up gain is about 8-fold.



TextFigure Module

Hierarchical Vector Quantization

- We use a hierarchical clustering technique to speed up this process.
- We use vector quantization for the same purpose
- but with a slightly different approach.
- Then according to the nearest cluster in the first step we compare against
- 16 other clusters to find the nearest cluster (Figure 3, c).
- We pre-compute clusters using k-means algorithm.
- Our experiments show that the proposed hierarchical clustering technique leads to a negligible loss of 0.001 in mAP.







Hierarchical Vector Quantization

- We use a hierarchical clustering technique to speed up this process .



• Evaluation metrics

Text



Rouge-L: 83.3 / 71.4 / 76.9

• Evaluation metrics

Text the cat is sleeping on bed the brown cat is sitting on bed Rouge-L: 83.3 / 71.4 / 76.9 $|\mathbf{P}-\mathbf{Q}|$ Rouge $\times e$ Q consider Page Difference •

- **P:** #Page_{pd}
- **Q**: #Page_{gd}

• Evaluation metrics



P: #Page_{pd} **Q**: #Page_{gd}

٠

consider Page difference

• Evaluation metrics



1st / 2nd

Model	Co-Train	w/ M	odule	Те	ext		Figure		TextFigure
	TextFigure	Paraphrase	TextFigure	Rouge-L	w/ Page	LC-P	LC-R	LC-F1	Rouge-L
Baseline	X	X	X	27.2	21.8	13.2	21.9	16.5	3.6
	X	X	X	27.7	22.9	14.6	23.7	18.1	4.3
	XX	\checkmark	X	32.3	26.7	14.6	23.7	18.1	4.7
ЦСЕ	√	X	X	28.7	24.0	14.8	32.4	20.3	7.9
ПЭЕ	\checkmark	X	\checkmark	28.7	24.0	24.6	40.5	30.6	13.8
	\checkmark	\checkmark	X	33.6	28.2	14.8	32.4	20.3	8.2
	\checkmark	\checkmark	\checkmark	33.6	28.2	24.6	40.5	30.6	15.5

Model	Co-Train	w/ M	odule	Те	ext		Figure		TextFigure
	TextFigure	Paraphrase	TextFigure	Rouge-L	w/ Page	LC-P	LC-R	LC-F1	Rouge-L
Baseline	Х		Х	27.2	21.8	13.2	21.9	16.5	3.6
	Х		Х	27.7	22.9	14.6	23.7	18.1	4.3
	Х		Х		26.7	14.6			4.7
шст	\checkmark		Х		24.0	14.8			7.9
HSE	\checkmark		\checkmark		24.0	24.6			13.8
	\checkmark		Х		28.2	14.8			8.2
	\checkmark	\checkmark	\checkmark	33.6	28.2	24.6	40.5	30.6	15.5

- Hierarchical architecture extracts slide
 - Helps both text quality and figure retrieval

Model	Co-Train	w/ M	odule	Те	ext		Figure		TextFigure
	TextFigure	Paraphrase	TextFigure	Rouge-L	w/ Page	LC-P	LC-R	LC-F1	Rouge-L
Baseline	Х	Х	Х	27.2	21.8	13.2	21.9	16.5	3.6
	X	X	Х	27.7	22.9	14.6	23.7	18.1	4.3
	Х	\checkmark	Х	32.3	26.7	14.6			4.7
шст		X	Х	28.7	24.0	14.8	32.4	20.3	7.9
HSE	\checkmark		\checkmark		24.0	24.6			13.8
	\checkmark	\checkmark	Х	33.6	28.2	14.8			8.2
	\checkmark	\checkmark	\checkmark	33.6	28.2	24.6	40.5	30.6	15.5

- **Paraphrasing module** rewrites sentences into slide-style
 - Better **text** as a slide

Model	Co-Train	w/ M	odule	Те	ext		Figure		TextFigure
	TextFigure	Paraphrase	TextFigure	Rouge-L	w/ Page	LC-P	LC-R	LC-F1	Rouge-L
Baseline	Х	Х	Х	27.2	21.8	13.2	21.9	16.5	3.6
	X	X	Х	27.7	22.9	14.6	23.7	18.1	4.3
	Х		Х		26.7	14.6			4.7
	\checkmark		X	28.7	24.0	14.8	32.4	20.3	7.9
HSE	\checkmark		\checkmark		24.0	24.6			13.8
	\checkmark		Х		28.2	14.8			8.2
	\checkmark	\checkmark	\checkmark	33.6	28.2	24.6	40.5	30.6	15.5

- Co-train with **TextFigure constrain**
 - Learns the **correlation** between text and figure

Model	Co-Train	w/ M	odule	Те	xt		Figure		TextFigure
	TextFigure	Paraphrase	TextFigure	Rouge-L	w/ Page	LC-P	LC-R	LC-F1	Rouge-L
Baseline	Х	Х	Х	27.2	21.8	13.2	21.9	16.5	3.6
	X	Х	Х	27.7	22.9	14.6	23.7	18.1	4.3
	Х		Х		26.7	14.6			4.7
		X	Х	28.7	24.0	14.8	32.4	20.3	7.9
HSE	\checkmark		\checkmark		24.0	24.6	40.5	30.6	13.8
	\checkmark		Х		28.2	14.8			8.2
	\checkmark	\checkmark	\checkmark	33.6	28.2	24.6	40.5	30.6	15.5

- **TextFigure module** removes unrelated or adds related
 - Benefits **figure retrieval** a lot

Model	Co-Train	w/ M	odule	Те	ext		Figure		TextFigure
	TextFigure	Paraphrase	TextFigure	Rouge-L	w/ Page	LC-P	LC-R	LC-F1	Rouge-L
Baseline	Х	Х	Х	27.2	21.8	13.2	21.9	16.5	3.6
	X	X	Х	27.7	22.9	14.6	23.7	18.1	4.3
	Х		Х		26.7	14.6			4.7
	\checkmark		X		24.0	14.8			7.9
HSE	\checkmark		\checkmark		24.0	24.6			13.8
	\checkmark		Х		28.2	14.8			8.2
	\checkmark	\checkmark	\checkmark	33.6	28.2	24.6	40.5	30.6	15.5

- Combines both **Paraphrasing** and **TextFigure** module
 - Fully improves on **all aspects of metrics**

Introduction

- We propose a novel multi-label conditional alignment methodology to bridge domain divergence while preserving the discriminability of the features .
- Mcar : multi-label conditional distribution alignment
- and detection regularization model
- Minimize the cross-domain feature distribution gaps .
- A whole image can have complex multimodal structures .
- Global (image-level) feature alignment (image-level)

Category Prediction based Regularization

- What is the structure of the graph ?

- We propose a novel category prediction mechanism for object detection .
- Each proposal will be classified as a regressor r .
- Region proposal network (rpn) 23-28 august zÃ,zÃ,
 Loss function := + (x)





Adaptation from Clear to Foggy Scenes.

Cross-domain detection from real to virtual image scenarios
 Domain adaption from normal / clear images to foggy image
 Pascal voc , pascal voc to comic



Ablation Study

Qualitative results : quantitative results 23-28 august zĂ,zĂ,
 Adacoseg : adaptive feature visualization with mutual regularization----p. zhao et al.
 We use the foggy cityscapes dataset as the target domain .
 Train on labeled data in the target domain
 Multiple auxiliary loss terms in the proposed learning objective



	Method	MC P	E perior	rider	144	truck	bas	17639	motorbike	hicycle	mAP
1000	Source-only		25.1	32.7	31.9		21.9	9.1	21.7	29.1	25.4
100	BDC-Faster [31]		281.4	37.2	42.4	21.2	28.2	12.3	22.6	28.9	27.5
1000	DA-Faster [2]		25.0	31.0	40.5	22.1	35.3	23.2	25.0	27.1	22.6
a state	SC-DA [44]		38.5	38.0	48.5	26.5	39.0	23.3	28.0	33.6	35.8
	MAF [17]		28.2	38.5	41.9	21.8	29.9	31.1	29.2	33.0	54.0
100 000	SW-DA [11]		36.2	35.3	43.5	30.0	20.9	42.3	32.6	24.5	34.3
22	DD-MRL 19		30.6	40.5	44.3	27.2	35.4	34.5	25.4	32.2	34.6
100	MTOR [1]		30.6	41.4	44.0	21.9	38.6	43.6	28.3	35.6	35.1
100	Dense DA [40]		33.2	44.2	44.8	28.2	41.8	25.7	30.5	36.5	36.0
	SCL [34]		31.6	44.0	44.8	38.4	41.8	49.7	33.6	36.2	37.9
	AND ARE LOWING	V.	31.7	42.5	41.5	32.3	41.4	33.0	32.4	36.5	36.6
	Not (en (Conte)	¥ 4	32.0	-12.1	41.9	31.3	44.3	43.4	37.4	36.6	35.8
	Train-ou-Target		50.0	36.2	49.7	31.7	33.2	45.9	37.4	35.6	\$1.3

Introduction

- What is a good emotion classification task ? - We use the context principle for emotion recognition . - Context 1 : incorporating cues from different modalities - Multimodal emotion recognition (cvpr 2020) - Not asking for the meaning of a word in isolation and instead of finding the meaning in isolation .

Network Architecture

- How to train your neural network ?

- To train the soft margin loss function :
- We combine the two loss functions , lmultiplicative (from eq . 1) .

- + λ2lclassification



Datasets

We present a comparison with other datasets.
 The apparent emotional states of the people
 How do we evaluate the annotation process ?
 How do we evaluate the friendliness ?

fmages	CAER-S	70,000 images	70.000	TV Shows	7 Categories	Yes
Videos	AFEW [15] CAER [16] IEMOCAP [2] GroupWalk	1.809 clips 13,201 clips 12 hts 45 clips(10 mins each)	1,809 13,201	Movie TV Show TV Show Real Settions	7 Categories 7 Categories 4 Categories 4 Categories	No Yes Yes

Analysis and Discussion

- Emotic dataset . emotic dataset was collected for

- Two-stream network (two-stream) [2]

- Gcn (ours) depth-based (ours)

- Groupwalk dataset was difficult to test on groupwalk .

Labels	Kosti et al.[27]	Zhang et al.[58]	Lee et al.[**]	Emo	tiCon
				GCN-Based	Depth-Based
Affection	27.85	46.89	19.9	36,78	45.23
Anger	09.49	10.87	11.5	14.92	15.46
Annovance	14.05	11.23	16.4	18,45	21.92
Anticipation	58.64	62.64	\$3.05	68,12	72.12
Aversion	07.48	5.93	16.2	16.48	17.81
Confidence	78.35	72.49	32.34	59.23	68.65
Disapproval	14.97	11.28	16.04	21.21	19.82
Disconnection	21.32	26.91	22.80	25.17	43.12
Disquietment	16.89	16.94	17.19	16,41	18,73
Doubt/Confusion	29.63	18.68	28.98	33.15	35.12
Embarrassment	03.18	1.94	15.68	11.25	14.37
Engagement	87.53	88.56	46.58	90.45	91.12
Esteem	17.73	13.33	19.26	22.23	23.62
Excitement	77.16	71.89	35.26	82.21	83.26
Fatigue	09,70	13.26	13.04	19,15	16.23

SELF-ADVERSARIAL LEARNING

For a training set with n real samples , we have
Sal (ours) (a) sal
How to suffer from the reward sparsity ?
Sal (ours) 3 (ours)



TRAINING

The comparative discriminator can offer more informative learning signals from the comparative discriminator .
 How to enhance the generalization ability of the comparative discriminator ?

- E (pz (z) , m)



COMPARATIVE DISCRIMINATOR

- The self-improvement mechanism corresponds to the comparative discriminator . - How to construct the model to supervise the model ? - (goodfellow et al . , 2014)

RESULTS IN REAL DATA - Table 3 . the results of coco image caption





• TextFigure Module (**w/o** vs **w/**)

INTRODUCTION

- Decouple the model training stage and search stage
- Specialized sub-nets âl sub-nets + sub-nets
- We extensively evaluated the effectiveness of ofa on imagenet - How to deploy different hardware efficiency constraints ?
- We propose a progressive shrinking algorithm for once-for-all.

INTRODUCTION

- Decouple the model training stage and search stage - Specialized sub-nets are sub-nets + sub-nets - We extensively evaluated the effectiveness of ofa on imagenet - How to deploy different hardware efficiency constraints ? - We propose a progressive shrinking algorithm for once-for-all.



Method

- Epnet : enhancing point features with image semantics
- Image feature in a point-wise manner .
- Li-fusion rpn effectively combines the lidar point feature
- We combine the point features si with the aid of our li-fusion module .

Method

Epnet : enhancing point features with image semantics
 Image feature in a point-wise manner .
 Li-fusion rpn effectively combines the lidar point feature

- We combine the point features si with the aid of our li-fusion module



Priority Lists

Each cell is linked to a list of templates
Each root has a limited budget of locations
How to balance proposals among all locations ?
We propose a score adjustment process .

Method	Ours	Ours	Ours	FTVQ [2]	DPM V5 [21]	
Frequency	100Hz	30Hz	15Hz	2Hz	0.07Hz	
aeroplane	0.1630	0.2695	0.3029	0.3320	0.3318	
bicycle	0.3563	0.5735	0.5946	0.5933	0.5878	
bird	0.0021	0.0909	0.0909	0.1027	0.1019	
boat	0.0303	0.0303	0.1141	0.1568	0.1801	
bottle	0.0909	0.1938	0.2425	0.2664	0.2535	
bus	0.2989	0.4130	0.4720	0.5129	0.5056	
car	0.2505	0.4240	0.4996	0.5373	0.5271	
cat	0.1368	0.1725	0.1931	0.2251	0.1904	
chair	0.0909	0.0909	0.1053	0.2010	0.2046	
COW	0.0909	0.1062	0.1994	0.2432	0.2444	
diningtable	0.1743	0.2500	0.2510	0.2685	0.2750	
dog	0.0507	0.1159	0.1159	0.1260	0.1238	
horse	0.2724	0.4735	0.5539	0.5651	0.5709	

Priority Lists

Each cell is linked to a list of templates
 Each root has a limited budget of locations
 How to balance proposals among all locations ?
 We propose a score adjustment process .



Evaluation on Various Target Tasks

- Meta-networks trained by our meta-training scheme (meta-networks)
- The first source model is trained on tinyimagenet .
- We use 34 layer resnet as a source and target model , respectively . - Ours needs only 50 samples per class

Evaluation on Various Target Tasks

- Meta-networks trained by our meta-training scheme (meta-networks)
- The first source model is trained on tinyimagenet .
- We use 34 - layer resnet as a source and target model , respectively .
- Ours needs only 50 samples per class

Source task	TinyImageNet		ImageNet				
Target task	CIFAR-100	STL-10	CUB200	MIT67	Stanford40	Stanford Dog	
Scratch	67.69+=22	65.18.com	42.15.015	48.91 acto	36.93	58.08.0.5	
LWF	69.231800	68.64205	45.52.iom	53.73azze	39.73+++	65.33	
AT (one-to-one)	67.54:04	74.19_02	\$7.74±LIT	59.18:10	59.29 ± mm	69.70±0m	
LwF+AT (one-to-one)	68.75	75.06	58.90at.12	61.42	60.20a.cm	72.6740.5	
FM (single)	69.40 sat	75.00 en.m	47.60±a11	55.15 ment	42.9311.0	65.05	
FM (one-to-one)	69.97::s24	76.38±1.0	48.93::0.40	54,88:134	44.50±±m	67.25±0m	
L2T-w (single)	70.27	74.35	51.95	60.41	46.25 ± im	69.16.40.20	
L2T-w (one-to-one)	70.02+++	76.42 eest	56.61	59.78+1m	48.19+++	69.84 a.m	
1.2T-ww (all-te-all)	70,96:sst	78.31	65.05.1.0	64.85	63.08	78.08	

• Paraphrasing Module (w/o vs w/)



Introduction



Related work

- Action proposals is an essential part of many methods for action detection, explored by a number of recent
 More related to our work, previous methods [9, 18, 24, 34, 35] explore the temporal order, either by predicting the exact order of consecutive
- frames [18, 35] or verifying their partial order [9, 24, 34].
- In the video domain, motion has been used as a cue
- for learning video representations in [1, 26, 33, 7]. - The notion of actionness was first introduced in [5] as a

confidence measure of intentional bodily movement of biological agents.



Related work

Action detection is a key tool for action detection
 Predicting the exact order of consecutive frames :
 Motion has been used as a cue .
 Actionness was first introduced in biological agents



Base Architecture

 The feed-forward layers capture the domainspecific and -independent information by using priva output layers for each domain and one shared output layer.

B-PER HER O SLOC

- Word embeddings are derived from a combination GloVe (Pennington et
- al., 2014) and FastText (Bojanowski et al., 2017) pre-trained word
- embeddings, as used in (Ma and Hovy, 2016).
- The global objective function is the combination of
- the NER loss function and domain loss:
- The domain classification objective is to minimize the crossentropy loss Ldomain(x,
- yd) for an input x with domain label yd.
- We propose a new architecture based on the BiLSTMâ22CRF model tailored to the three proposed experimental setups.

Base Architecture

- Use private output layers for each domain
- (ma et al . , 2017)
- The global objective function is the combination of the ner loss
 The domain classification objective is to minimize the crossentropy loss.
- We propose a new architecture based on the bilstm model .



Conclusions

- In this paper, we proposed two parameterized benchmark games in which EFCE exhibits interesting behaviors.
- We also provided an alternative saddle-point formulation of EFCE and demonstrated its merit with a simple subgradient method
- which outperforms standard LP based methods.
- We analyzed those behaviors both qualitatively and quantitatively, and
- isolated two ways through which a mediator is able
- to compel the agents to follow the recommendations.
- We hope that our analysis will bring attention to some of the computational and practical uses of EFCE, and that our benchmark games will be useful for evaluating future algorithms for computing EFCE in large games.

Conclusions

- We proposed two parameterized games in which efce exhibits interesting behaviors .
 We propose a saddle-point formulation of efce
- we propose a sauce-point formulation or erce
 Two ways to compel the agents to follow the recommendations
- We show that our analysis will be useful for computing efce in large games

• Applying **Design Ideas**



Conclusion

- DOC2PPT serves as a **multi-modal summarizer** to generate slide from academic documents
- We propose hierarchical architecture, text-figure constrain, and paraphrasing module to improve the quality of slide generation
- DOC2PPT **provides useful outline and flow** to make building a slide more efficiency

